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Project #4: KSM (Kernel Samepage Merging)



- KSM (Kernel Same page Merging) is a memory de-duplication feature that enables the kernel to consolidate identical memory pages into a single shared page across multiple processes.
- Merged pages are write-protected, therefore attempts to modify the merged page would cause a page fault.
- A modification to a merged page results in a copy-on-write action, thus preserving the integrity of the original shared page.



Process I

- $VPN(A) \rightarrow PFN(B)$
- Process 2
 - $VPN(C) \rightarrow PFN(D)$
- PFN (B) and PFN (D) has same contents







(1) ksmd Scans Process 1(2) Hash PFN B



(1) ksmd Scans Process 1(2) Hash PFN B(3) Lookup KSM Meta







(1) ksmd Scans Process 1
(2) Hash PFN B
(3) Lookup KSM Meta
(4) Not found, update KSM Meta
(5) ksmd Scans Process 2
(6) Hash PFN D





(1) ksmd Scans Process 1
(2) Hash PFN B
(3) Lookup KSM Meta
(4) Not found, update KSM Meta
(5) ksmd Scans Process 2
(6) Hash PFN D
(7) Lookup KSM Meta
(8) Found!, update KSM Meta













I. Implement the ksm() (70 points)

- Your task is to implement a new system call named ksm()
- int ksm(int *scanned, int *merged);
 - scanned:Total number of scanned frames
 - merged:Total number of merged frames
 - return value: Total number of free frames ('freemmem')
- System call number is assigned to 24 (already done in branch pa4)
- The initial free memory could differ due to implementation details.

I. Implement the ksm() (70 points)

- Scan the page frames used by each user process p from the virtual address 0 to p->sz. The region will contain code, data, heap, and stack (+ stack guard) pages. Exclude trampoline, trapframe, kernel stack, and page table pages from scanning as they are not targets for KSM.
- You can assume that a single physical frame can be shared by up to 16 different virtual pages, except for the zero-page. There is no limit on the number of virtual pages that can share the zero-page.
- When performing ksm(), exclude the page frames used by init process (pid 1), the sh process (pid 2), and the process invoking the ksm() system call itself from scanning. Assume that the shell process always runs with pid 2.
- Duplicated page frames are merged only through the ksm() system call; they should not be merged at the time of page allocation.
- There should be no memory leak. The freemem value should remain identical before and after executing a program.
- ksm3 user program should run with background ksmd running. To run a process background, run 'ksmd &'

User Virtual Memory





- You are required to preallocate a "zero-page" in the system which is filled with zeroes. Since BSS and heap pages are initialized to zero, those pages can be mapped to the zero-page.
- There is no limit on the number of virtual pages that can share the zero-page.

ksml



*The scanned & freemem value could differ due to implementation detail

ksml (with debug message)



ksml (with debug message)

pid 3: ksmd starts			
ksm: scanned=0, merged=0, freemem=31456			
KSMD: after forking child 4			
[KSM] ===== Scanning Process[4] ===== =====			
[KSM] Scanning VPN(0): Unique Page (PA: 0x0000000087f49000)			
[KSM] Scanning VPN(1): Mapped to zero page			
[KSM] Scanning VPN(2): Mapped to zero page			
[KSM] Scanning VPN(3): Mapped to zero page			
[KSM] Scanning VPN(4): Mapped to zero page			
[KSM] Scanning VPN(5): Mapped to zero page			
[KSM] Scanning VPN(6): Unique Page (PA: 0x0000000087f51000)			
ksm: scanned=7, merged=5, freemem=31448			
KSMD: after forking child 5			
[KSM] ===== ==== Scanning Process[4] ===== =====			
[KSM] Scanning VPN(0):			
[KSM] Scanning VPN(1): Does nothing because it has been			
[KSM] Scanning VPN(2):			
[KSM] Scanning VPN(3): merged or scanned			
[KSM] Scanning VPN(4):			
[KSM] Scanning VPN(5):			
[KSM] Scanning VPN(6):			
[KSM] ===== ==== Scanning Process[5] ===== =====			
[KSM] Scanning VPN(0): Hash match, (old pa 0x0000000087f4c000 -> new pa 0x000000087f49000) (RC -> 2)			
[KSM] Scanning VPN(1): Mapped to zero page			
[KSM] Scanning VPN(2): Mapped to zero page			
[KSM] Scanning VPN(3): Mapped to zero page			
[KSM] Scanning VPN(4): Mapped to zero page			
[KSM] Scanning VPN(5): Mapped to zero page			
[KSM] Scanning VPN(6): Unique Page (PA: 0x0000000087f6e000)			
ksm: scanned=14, merged=6, freemem=31441			

ksml (with debug message)

pid 3: ksmd starts			
ksm: scanned=0, merged=0, freemem=31456			
KSMD: after forking child 4			
[KSM] ===== ==== Scanning Process[4] ===== =====			
[KSM] Scanning VPN(0): Unique Page (PA: 0x000000087f49000)			
[KSM] Scanning VPN(1): Mapped to zero page			
[KSM] Scanning VPN(2): Mapped to zero page			
[KSM] Scanning VPN(3): Mapped to zero page			
[KSM] Scanning VPN(4): Mapped to zero page			
[KSM] Scanning VPN(5): Mapped to zero page			
[KSM] Scanning VPN(6): Unique Page (PA: 0x0000000087f51000)			
ksm: scanned=7, merged=5, freemem=31448			
KSMD: after forking child 5			
[KSM] ===== Scanning Process[4] ===== =====			
[KSM] Scanning VPN(0):			
[KSM] Scanning VPN(1):			
[KSM] Scanning VPN(2):			
[KSM] Scanning VPN(3):			
[KSM] Scanning VPN(4):			
[KSM] Scanning VPN(5):			
[KSM] Scanning VPN(6): Alter IOIK, CHILU 5 and 4 has the same text area			
[KSM] ===== Scanning Process[5] ===== ====			
[KSM] Scanning VPN(0): Hash match, (old pa 0x0000000087f4c000 -> new pa 0x000000087f49000) (RC -> 2)			
[KSM] Scanning VPN(1): Mapped to zero page			
[KSM] Scanning VPN(2): Mapped to zero page			
[KSM] Scanning VPN(3): Mapped to zero page			
[KSM] Scanning VPN(4): Mapped to zero page Stack may differ			
[KSM] Scanning VPN(5): Mapped to zero page			
[KSM] Scanning VPN(6): Unique Page (PA: 0x0000000087f6e000)			
ksm: scanned=14, merged=6, treemem=31441			

Hints

- There are three major flows that you should modify
 - KSM flow
 - Page fault flow (copy-on-write)
 - Physical page release flow (process exit, exec, ...)
- Try to print as much debug message as possible
 - PFN
 - VPN
 - Which page is merged to which
 - Which page was released
 - Which page performed a CoW

2. Design Document (30 points)

- There are limitations in simply comparing the output of the user programs to genuinely check if the KSM was properly implemented.
- You should explain what you have considered, and what you have done.
- Requirements
 - Data structures
 - Overall flowchart
 - Algorithm design
 - Implementation details
 - Testing and validation

Tips

- Read Chap. 3, Chap. 4 of the <u>xv6 book</u> to understand RISC-V's virtual memory subsystem and page-fault exceptions in xv6.
- For your reference, the following roughly shows the amount of changes you need to make for this project assignment.
- Each "+" symbol indicates 1~10 lines of code that should be added, deleted, or altered.

kernel/defs.h	+
kernel/exec.c	+
kernel/proc.c	+
kernel/trap.c	+
kernel/vm.c	+
kernel/ksm.h	+++++
kernel/ksm.c	+++++++++++++++++++++++++++++++++++++

Restrictions

- For this project assignment, you can assume a uniprocessor RISC-V system (CPUS = 1) with a physical memory size of 128 MiB.
- Please use the qemu version 8.2.0 or later. To determine the qemu version, use the command: \$ qemu-system-riscv64 --version
- We will run qemu-system-riscv64 with the -icount shift=0 option, which enables aligning the host and virtual clocks. This setting is already included in the Makefile for the pa4 branch.
- You only need to change the files in the ./kernel directory (mostly to ksm.h and ksm.c files provided in the skeleton code). Any other changes outside the ./kernel directory will be ignored during grading.

Skeleton Code

- Skeleton Code
 - You should work on the pa4 branch of the xv6-riscv-snu repository as follows:

\$ git clone https://github.com/snu-csl/xv6-riscv-snu
\$ git checkout pa4

• The pa4 branch has a user-level utility program named ksmd, ksml, ksm2, ksm3 which can be built from the user/ksmd.c, user/kms1.c, user/ksm2.c, user/ksm3.c file

Notification

- Due
 - 11:59 PM, May 26 (Sunday)
- Submission
 - Run the make submit command to generate a tarball named xv6-pa4-{STUDENTID}.tar.gz in the xv6-riscv-snu directory
 - Upload the compressed file to the submission server
 - The total number of submissions for this project will be limited to 50
 - Only the version marked FINAL will be considered for the project score

Using GDB with QEMU

- In the xv6-riscv-snu directory,
- Run make qemu-gdb to run QEMU
- In another shell, run gdb-multiarch ./kernel/kernel
- gdb-multiarch automatically sets the target architecture to "riscv:rv64"





- In GDB, enter target remote :<port>
- You can find TCP port in the QEMU log

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csl@sys ~/injae/xv6-riscv-snu % make qemu-gdb

*** Now run 'gdb' in another window.

qemu-system-riscv64 -machine virt -bios none -kernel kernel/kernel -m 128M -smp 4 -nog raphic -global virtio-mmio.force-legacy=false -drive file=fs.img,if=none format=raw,id _x0 -device virtio-blk-device,drive=x0,bus=virtio-mmio-bus.0 -S -gdb tcp::26000

Type "show configuration" for configuration details. For bug reporting instructions, please see: <http://www.gnu.org/software/gdb/bugs/>. Find the GDB manual and other documentation resources online at: <http://www.gnu.org/software/gdb/documentation/>. For help, type "help". Type "apropos word" to search for commands related to "word"... Reading symbols from kernel/kernel... warning: File "/home/csl/injae/xv6-riscv-snu/.gdbinit" auto-loading has been declined by your `auto-load safe-path' set to "\$debugdir:\$datadir/auto-load". To enable execution of this file add add-auto-load-safe-path /home/csl/injae/xv6-riscv-snu/.gdbinit line to your configuration file "/home/csl/.gdbinit". To completely disable this security protection add set auto-load safe-path / line to your configuration file "/home/csl/.gdbinit". For more information about this security protection see the "Auto-loading safe path" section in the GDB manual. E.g., run from the shell: --Type <RET> for more, q to quit, c to continue without paging-info "(gdb)Auto-loading safe path" (gdb) target remote :26000 Remote debugging using :26000 0x00000000000000000 in ?? () (gdb)

- The xv6 virtual machine has stopped at 0x1000 (the very beginning of the text section)
- To continue, enter c in GDB

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csl@sys.snu.ac.kr

csl@sys ~/injae/xv6-riscv-snu % make qemu-gdb

*** Now run 'gdb' in another window.

qemu-system-riscv64 -machine virt -bios none -kernel kernel/kernel -m 128M -smp 4 -nog raphic -global virtio-mmio.force-legacy=false -drive file=fs.img,if=none,format=raw,id =x0 -device virtio-blk-device,drive=x0,bus=virtio-mmio-bus.0 -S -gdb tcp::26000

xv6 kernel is booting

hart 3 starting
hart 2 starting
hart 1 starting
init: starting sh
\$

(Running)

<http://www.gnu.org/software/gdb/bugs/>. Find the GDB manual and other documentation resources online at: <http://www.gnu.org/software/gdb/documentation/>. For help, type "help". Type "apropos word" to search for commands related to "word"... Reading symbols from kernel/kernel... warning: File "/home/csl/injae/xv6-riscv-snu/.gdbinit" auto-loading has been declined by your `auto-load safe-path' set to "\$debugdir:\$datadir/auto-load". To enable execution of this file add add-auto-load-safe-path /home/csl/injae/xv6-riscv-snu/.gdbinit line to your configuration file "/home/csl/.gdbinit". To completely disable this security protection add set auto-load safe-path / line to your configuration file "/home/csl/.gdbinit". For more information about this security protection see the "Auto-loading safe path" section in the GDB manual. E.g., run from the shell: --Type <RET> for more, q to quit, c to continue without paging-info "(gdb)Auto-loading safe path" (qdb) target remote :26000 Remote debugging using :26000 0x0000000000000000 in ?? () (gdb) c Continuing.

- To stop again, enter Ctrl-C in GDB
- Then the xv6 virtual machine stops immediately

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csl@sys ~/injae/xv6-riscv-snu % make qemu-gdb
*** Now run 'gdb' in another window.

qemu-system-riscv64 -machine virt -bios none -kernel kernel/kernel -m 128M -smp 4 -nog raphic -global virtio-mmio.force-legacy=false -drive file=fs.img,if=none,format=raw,id =x0 -device virtio-blk-device,drive=x0,bus=virtio-mmio-bus.0 -S -gdb tcp::26000

xv6 kernel is booting

hart 3 starting
hart 2 starting
hart 1 starting
init: starting sh
\$

(Stopped)

– 🗆 X csl@sys.snu.ac.kr For help, type "help". Type "apropos word" to search for commands related to "word"... Reading symbols from kernel/kernel... warning: File "/home/csl/injae/xv6-riscv-snu/.gdbinit" auto-loading has been declined by your `auto-load safe-path' set to "\$debugdir:\$datadir/auto-load". To enable execution of this file add add-auto-load-safe-path /home/csl/injae/xv6-riscv-snu/.gdbinit line to your configuration file "/home/csl/.gdbinit". To completely disable this security protection add set auto-load safe-path / line to your configuration file "/home/csl/.gdbinit". For more information about this security protection see the "Auto-loading safe path" section in the GDB manual. E.g., run from the shell: --Type <RET> for more, q to quit, c to continue without paging-info "(gdb)Auto-loading safe path" (gdb) target remote :26000 Remote debugging using :26000 0x0000000000000000 in ?? () (gdb) c Continuing. Thread 1 received signal SIGINT, Interrupt. mycpu () at kernel/proc.c:79 79 (gdb)

- Let's set a breakpoint at exec()
- Enter b exec in GDB

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csl@sys ~/injae/xv6-riscv-snu % make qemu-gdb

*** Now run 'gdb' in another window.

qemu-system-riscv64 -machine virt -bios none -kernel kernel/kernel -m 128M -smp 4 -nog raphic -global virtio-mmio.force-legacy=false -drive file=fs.img,if=none,format=raw,id =x0 -device virtio-blk-device,drive=x0,bus=virtio-mmio-bus.0 -S -gdb tcp::26000

xv6 kernel is booting

hart 3 starting
hart 2 starting
hart 1 starting
init: starting sh
\$

(Stopped)

– 🗆 X csl@sys.snu.ac.kr Reading symbols from kernel/kernel... warning: File "/home/csl/injae/xv6-riscv-snu/.gdbinit" auto-loading has been declined by your `auto-load safe-path' set to "\$debugdir:\$datadir/auto-load". To enable execution of this file add add-auto-load-safe-path /home/csl/injae/xv6-riscv-snu/.gdbinit line to your configuration file "/home/csl/.gdbinit". To completely disable this security protection add set auto-load safe-path / line to your configuration file "/home/csl/.gdbinit". For more information about this security protection see the "Auto-loading safe path" section in the GDB manual. E.g., run from the shell: --Type <RET> for more, q to quit, c to continue without paging-info "(gdb)Auto-loading safe path" (gdb) target remote :26000 Remote debugging using :26000 0x0000000000000000 in ?? () (gdb) c Continuing. Thread 1 received signal SIGINT, Interrupt. mycpu () at kernel/proc.c:79 79 (qdb) b exec Breakpoint 1 at 0x80004ec0: file kernel/exec.c, line 24. (gdb)

Enter c in GDB to resume the xv6 machine

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csl@sys ~/injae/xv6-riscv-snu % make qemu-gdb

*** Now run 'gdb' in another window.

qemu-system-riscv64 -machine virt -bios none -kernel kernel/kernel -m 128M -smp 4 -nog raphic -global virtio-mmio.force-legacy=false -drive file=fs.img,if=none,format=raw,id =x0 -device virtio-blk-device,drive=x0,bus=virtio-mmio-bus.0 -S -gdb tcp::26000

xv6 kernel is booting

hart 3 starting
hart 2 starting
hart 1 starting
init: starting sh
\$

(Running)

csl@sys.snu.ac.kr by your `auto-load safe-path' set to "\$debugdir:\$datadir/auto-load". To enable execution of this file add add-auto-load-safe-path /home/csl/injae/xv6-riscv-snu/.gdbinit line to your configuration file "/home/csl/.gdbinit". To completely disable this security protection add set auto-load safe-path / line to your configuration file "/home/csl/.gdbinit". For more information about this security protection see the "Auto-loading safe path" section in the GDB manual. E.g., run from the shell: --Type <RET> for more, q to quit, c to continue without paging-info "(gdb)Auto-loading safe path" (gdb) target remote :26000 Remote debugging using :26000 0x00000000000000000 in ?? () (gdb) c Continuing. Thread 1 received signal SIGINT, Interrupt. mycpu () at kernel/proc.c:79 79 (adb) b exec Breakpoint 1 at 0x80004ec0: file kernel/exec.c, line 24. (gdb) c Continuing.

– 🗆 X

- Run Is command in the xv6 machine
- Then the xv6 machine hits the breakpoint and stops right before starting exec() function

– c] X
ernel kernel/kernel -m 128M -smp 4 drive file=fs.img,if=none,format=ra io-mmio-bus.0 -S -gdb tcp::26000	-nog For mon w,id "Auto-T Type
	(gdb) t Remote
	(gdb) of Continue Continue Continue Continue (gdb) b Breakpo (gdb) of Continue [Switch
(Stopped) Thread arg 24 (gdb)
	ernel kernel/kernel -m 128M -smp 4 drive file=fs.img,if=none,format=ra io-mmio-bus.0 -S -gdb tcp::26000 (Stopped



More about GDB

- To learn GDB in detail, search for GDB on Google
- There are many useful videos about GDB in YouTube
- [JTJ의 리눅스탐험] GDB 활용하기

Thank you!