Operating Systems - Scheduling

Project #4

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2020.04.21.

Reminder) Late Submission policy

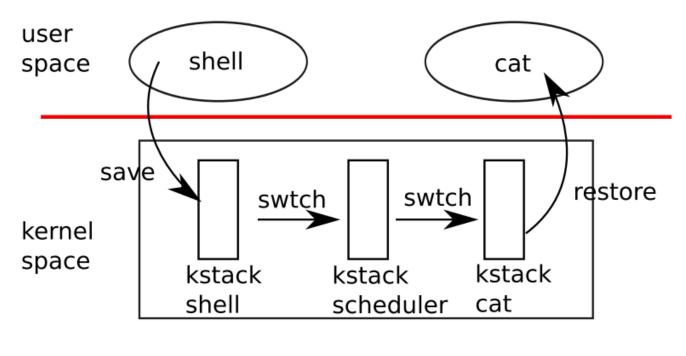
- You can use up to 5 slip days for this semester
 - You should explicitly declare the number of slip days to use in the Q&A board on the submission server
 - https://sys.snu.ac.kr/main.php?classIdx=I&menu=Board
- 25% penalty per day after slip day

Xv6 Process

- Process states (in proc.h)
 - Enum prostate { UNUSED, SLEEPING, RUNNABLE, RUNNING, ZOMBIE }
- UNUSED : Not used
- SLEEPING : Wait for I/O, wait(), or sleep()
- RUNNABLE : Ready to run
- RUNNING : Running on CPU
- ZOMBIE : Exited, wait for parent call wait()

Xv6 Scheduler

- Switching from one user process to another
 - In this example, xv6 runs with one CPU (One scheduler thread)



Kernel

Entering scheduler

- Entering scheduler when
 - I. Exiting process
 - 2. Sleeping process
 - 3. Yielding CPU (timer interrupt)

```
[csl@csl: xv6-riscv-snu]$ grep -nr "sched()"
kernel/proc.c:379: sched();
kernel/proc.c:511: sched();
kernel/proc.c:558: sched();
```

```
sched(void)
  int intena;
  struct proc *p = myproc();
  if(!holding(&p->lock))
    panic("sched p->lock");
  if(mycpu()->noff != 1)
    panic("sched locks");
  if(p->state == RUNNING)
    panic("sched running");
  if(intr_get())
    panic("sched interruptible");
 intena = mycpu()->intena;
  swtch(&p->context, &mycpu()->scheduler);
 mycpu()->intena = intena;
```

Xv6 Scheduler

- A simple scheduling policy, which runs each process in turn.
 - This policy is called round robin
- Each CPU calls scheduler() after setting itself up.
- Scheduler never returns. It loops, doing
 - choose a process to run.
 - swtch to start running that process.
 - eventually that process transfers control
 - via swtch back to the scheduler
- in kernel/proc.c
 - void scheduler(void)

Xv6 Scheduler in proc.c

- The scheduler loops over the process table looking for a p-> state == RUNNABLE
- Once it finds a process, it sets the per-CPU current process(c->proc)
- Marks the process as RUNNING, and then calls swtch to start running

```
for(p = proc; p < &proc[NPROC]; p++) {
    acquire(&p->lock);
    if(p->state == RUNNABLE) {
        // Switch to chosen process. It is the process's job
        // to release its lock and then reacquire it
        // before jumping back to us.
        p->state = RUNNING;
        c->proc = p;
        swtch(&c->scheduler, &p->context);

        // Process is done running for now.
        // It should have changed its p->state before coming back.
        c->proc = 0;
    }
    release(&p->lock);
```

Timer interrupt in trap.c

 RISC-V has three modes in which the CPU can execute instructions machine mode, supervisor mode, and user mode

Time interrupt in xv6 is machine mode.

The yield calls in usertrap and kerneltrap cause this switching

Project#4 – Linux 2.4 Scheduler

- In this project, you have to
 - I. Implement the nice() system call
 - 2. Implement a Simplified Linux 2.4 Scheduler
 - 3. Revise the getticks() system call

Due date is May 3 (Sunday) 11:59PM

nice system call - I

- int nice(int pid, int inc)
 - Add inc to the current nice value of the process pid.
 - The range of nice value is -20 to 19
 - A higher nice value means a lower priority
 - When a process is created, its nice value is the same as the parent's
 - The nice value of the init process is zero
 - if pid is positive, then the nice value of process with the specified pid is changed.
 - If pid is zero, then the nice value of the calling process if is changed.

nice system call - 2

return value

- On success, zero is returned.
- On error, I is returned.
 - pid is negative.
 - There is no valid process that has pid.
 - The resulting nice value exceeds the range [-20, 19]

Simplified Linux 2.4 scheduler - I

- On every timer ticks, the $p \rightarrow counter$ value is decremented by I
 - When $p \rightarrow counter$ is 0, the process used up all its time slice
 - and the scheduler is invoked!
- When the scheduler is invoked, the scheduler picks the process that has maximum goodness value.

```
goodness(p) = 0 ,if p \rightarrow counter == 0 , otherwise
```

Simplified Linux 2.4 scheduler - 2

- If there are no runnable processes, the scheduler busy-waits in current epoch
- When the $p \rightarrow counter$ value of all the runnable process will become 0,
 - The scheduler start new epoch, and reset the time slice for all processes

```
For runnable processes p \rightarrow counter = ((20 - (p \rightarrow nice)) >> 2) + 1

For blocked processes (when p \rightarrow counter is not 0) p \rightarrow counter = (p \rightarrow counter >> 1) + ((20 - (p \rightarrow nice)) >> 2) + 1
```

Simplified Linux 2.4 scheduler - 3

When fork is executed, the process' remaining time slice is split

```
    parent: p → counter >> 1
    child: (p → counter + 1) >> 1
```

 Once scheduled, the running process is not preempted until the end of its time slice

Revise getticks system call - I

- int getticks(int pid)
 - The getticks system call returns the number of ticks used by the process pid
 - The skeleton code already includes an implementation of the getticks() system call for the default round-robin scheduler.
 - Pre-implemented getticks system call doesn't return the correct number of ticks
 - So, you revise it

getticks system call - 2

- int getticks(int pid)
 - If pid is positive, return the number of ticks used by the process.
 - If pid is zero, return the number of ticks used by the calling process.

return value

- On success, the number of ticks is returned.
- On error, I is returned.

Project #4 – submission

 In this project, you have to submit a report explaining your implementation. (+ source code)

- These must be included in your report.
 - How to implement scheduling algorithm
 - You must explain details about your schedule
 - How to make sure the getticks() system call returns the correct number of ticks
 - Schedtest2 result (make qemu-log result, xv6.log) and an explanation
 - Schedtest2 image (make png result)

Project #4 – restrictions

- The CPUS is already set to 1 in the Makefile
- Your implementation should pass the following test programs available on xv6
 - usertests
 - schedtest l
 - Schedtest2
- Do not add any system calls other than nice() and getticks()
- You only need to modify those files in the ./kernel directory

You may want to see...

- modification
 - proc.c
 - trap.c

- In xv6 book
 - Chapter 4.1 ~ 4.4 (about trap)
 - Chapter 6 (about scheduling)

Example - boot

```
p \rightarrow counter = ((20 - (p \rightarrow nice)) >> 2) + 1
```

- The init process' nice is zero, which is the default value for $p \rightarrow nice$, and the counter is six according to the formula above.
- When you first boot up, $p \rightarrow nice$ should be set to zero, and the counter should be parent, child all 3 because it was inherited from init.

And because there is no runnable process, do not enter the new epoch

and do not reassign the counter.

```
xv6 kernel is booting
init: starting sh
$
1 (nice:0, counter:3) sleep init
2 (nice:0, counter:3) sleep sh

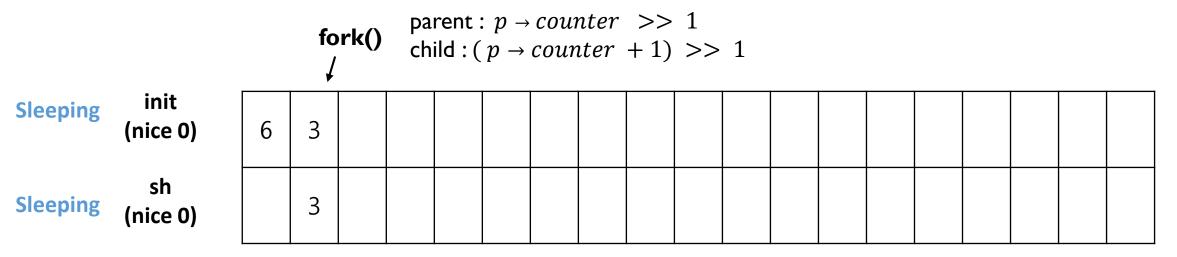
1 (nice:0, counter:3) sleep init
2 (nice:0, counter:3) sleep sh

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2 (nice:0, counter:3) sleep sh

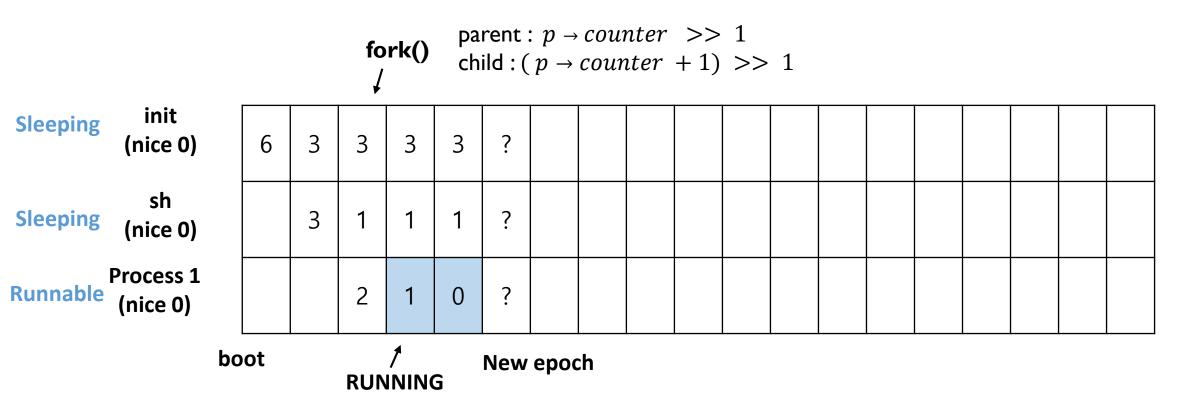
1 (nice:0, counter:3) sleep init
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2 (nice:0, counter:3) sleep sh

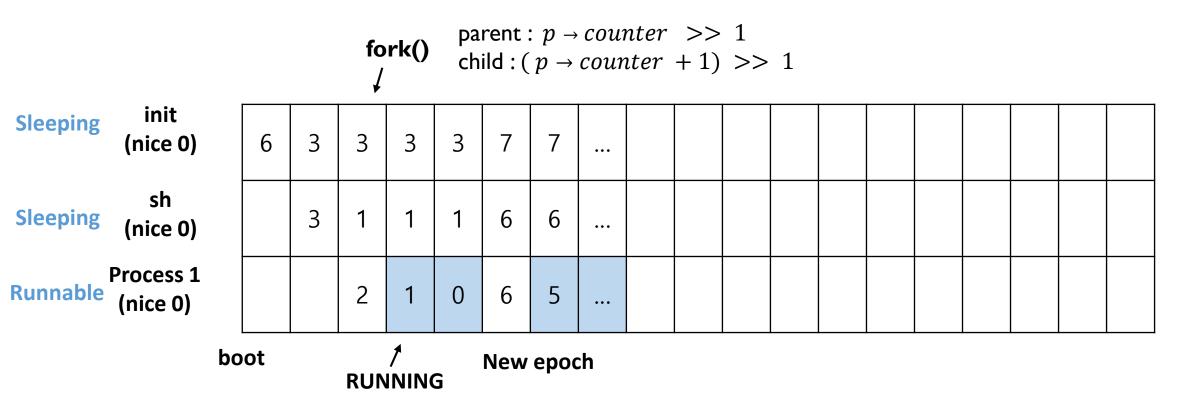
1 (nice:0, counter:3) sleep init
2 (nice:0, counter:3) sleep init
2 (nice:0, counter:3) sleep sh
```

Busy waiting



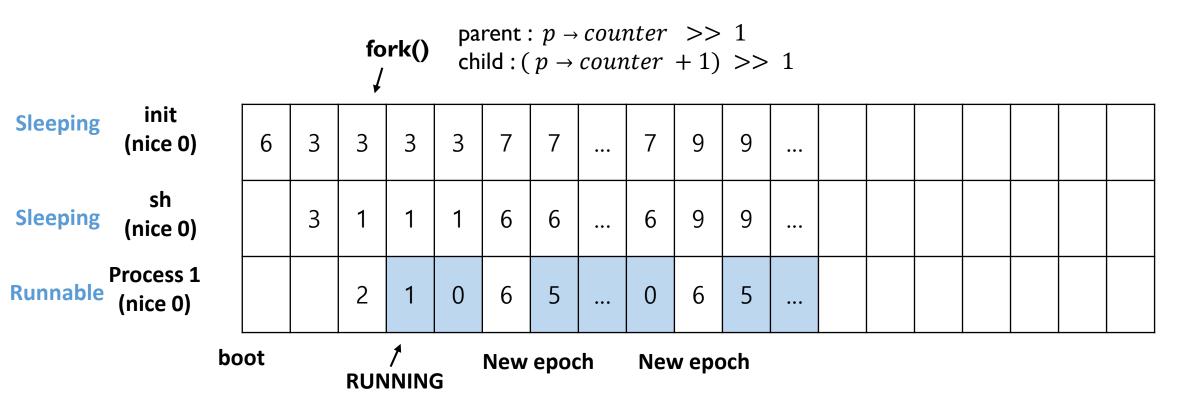
boot Busy waiting





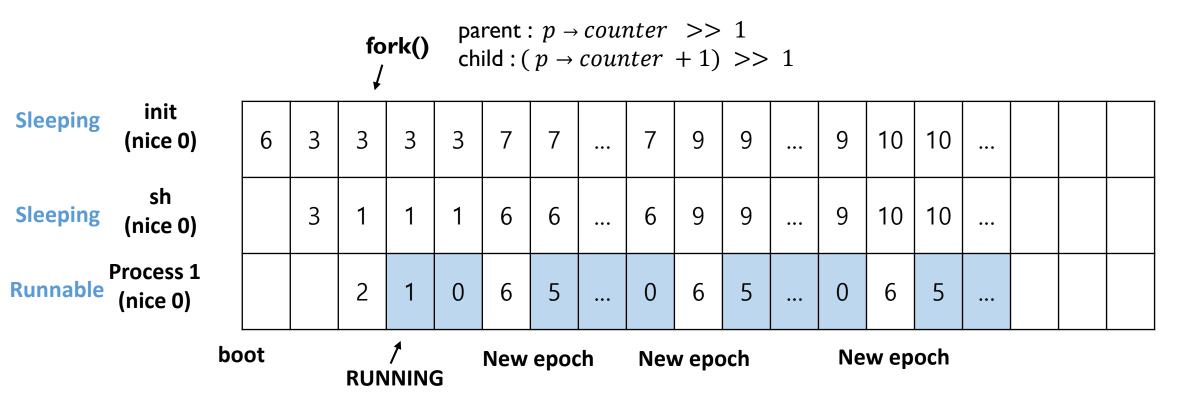
For runnable process
$$p \rightarrow counter = ((20 - (p \rightarrow nice)) >> 2) + 1$$

For blocked process $p \rightarrow counter = (p \rightarrow counter >> 1) + ((20 - (p \rightarrow nice)) >> 2) + 1$



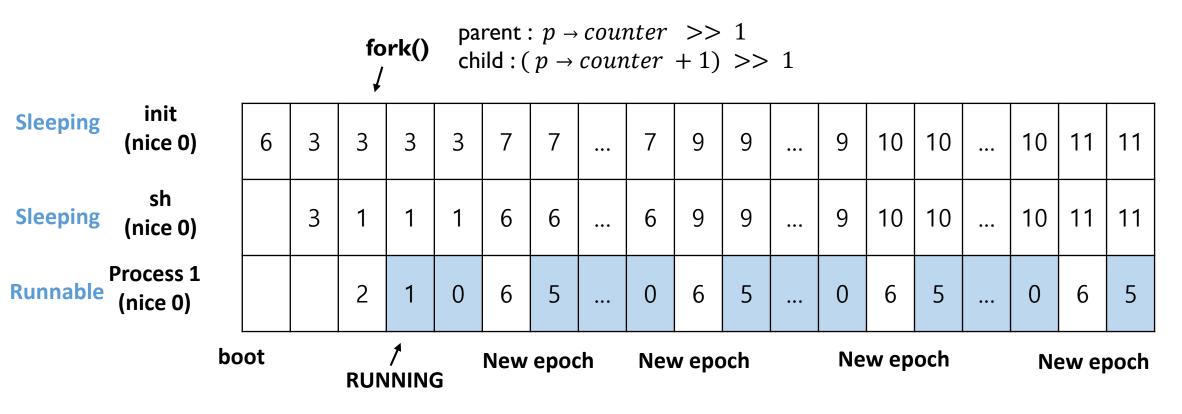
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For runnable process
$$p \rightarrow counter = ((20 - (p \rightarrow nice)) >> 2) + 1$$

For blocked process $p \rightarrow counter = (p \rightarrow counter >> 1) + ((20 - (p \rightarrow nice)) >> 2) + 1$

Schedtest2

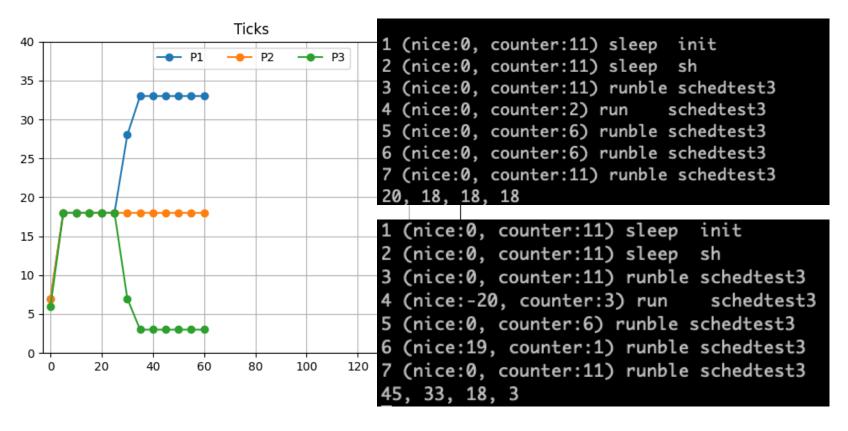
```
26 #define P 5 // period: 5 sec = 50 ticks
28 void
 9 main(int argc, char *argv[])
    int pid1, pid2, pid3, logger;
    if ((pid1 = fork()) == 0)
      while (1);
    if ((pid2 = fork()) == 0)
      while (1);
    if ((pid3 = fork()) == 0)
      while (1);
    if ((logger = fork()) == 0)
      int sec = 0;
     int p1 = 0, p2 = 0, p3 = 0; // the previous ticks
      int t1, t2, t3;
      while (1)
        t1 = getticks(pid1);
        t2 = getticks(pid2);
        t3 = getticks(pid3);
        printf("%d, %d, %d, %d\n", sec, t1 - p1, t2 - p2, t3 - p3);
        p1 = t1;
        p2 = t2;
        p3 = t3;
        sleep(P * 10);
        sec += P;
```

```
sleep(300);
nice(pid1, -20);
nice(pid3, 19);
sleep(300);
nice(pid1, 5);
nice(pid3, -4);
sleep(300);
nice(pid1, 5);
nice(pid3, -5);
sleep(300);
nice(pid1, 5);
nice(pid3, -5);
sleep(300);
sleep(100);
kill(logger);
kill(pid1);
kill(pid2);
kill(pid3);
wait(0);
wait(0);
wait(0);
wait(0);
exit(0);
```

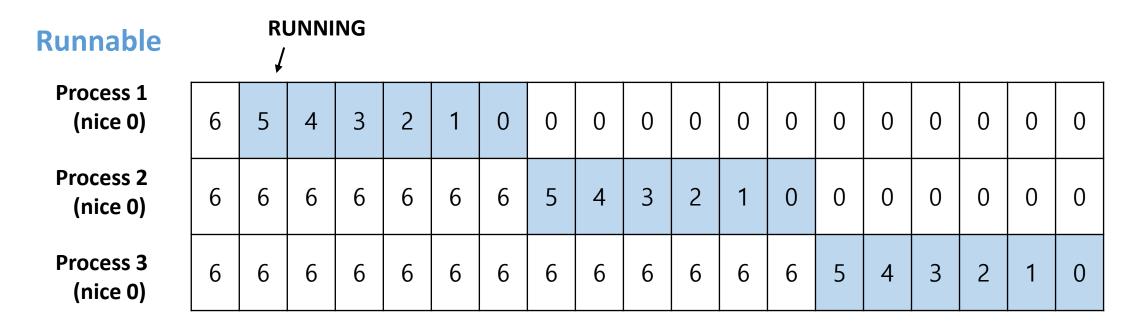
Example – schedtest2

If you have a process with a nice value of -20, 0, 19, what order is it sche duled? (PI:0, P2:0, P3:0 -> PI: -20, P2:0, P3:19)

```
xv6 kernel is booting
init: starting sh
$ schedtest2
0, 7, 7, 6
5, 18, 18, 18
10, 18, 18, 18
15, 18, 18, 18
20, 18, 18, 18
25, 18, 18, 18
30, 28, 18, 7
35, 33, 18, 3
40, 33, 18, 3
45, 33, 18, 3
50, 33, 18, 3
55, 33, 18, 3
60, 33, 18, 3
```



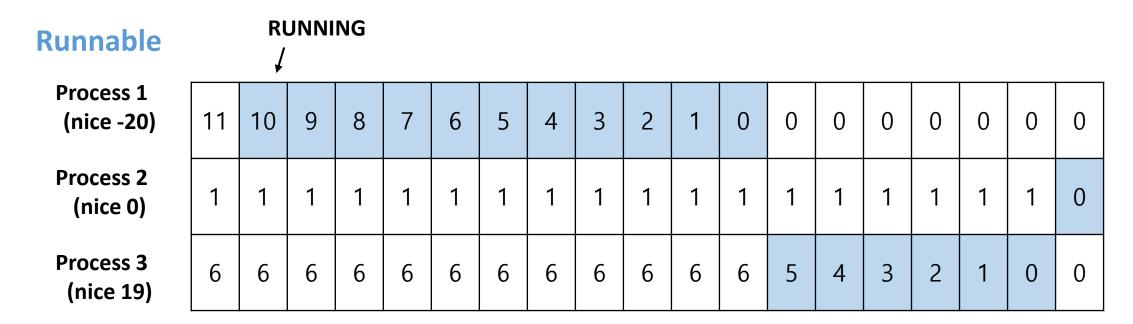
Phase I PI:0, P2:0, P3:0



new epoch end epoch

For runnable process $p \rightarrow counter = ((20 - (p \rightarrow nice)) >> 2) + 1$

Phase 2 PI: -20, P2:0, P3:19

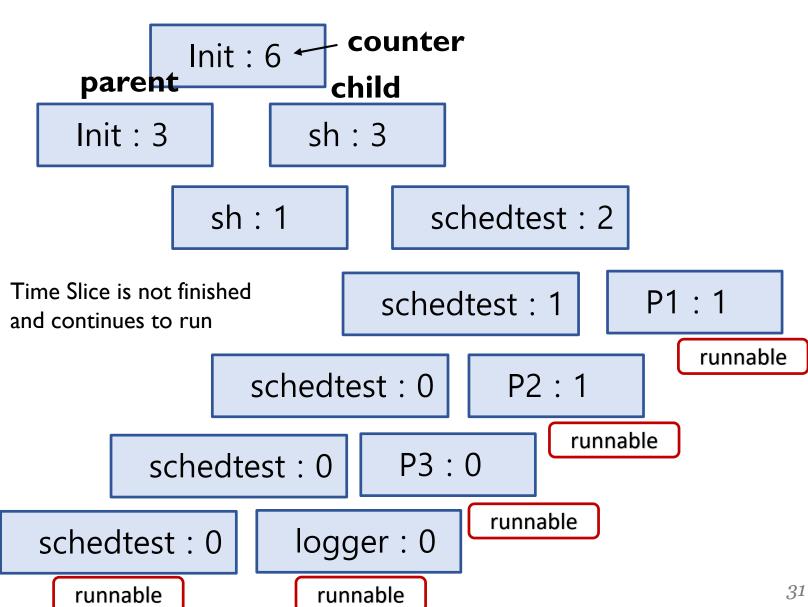


new epoch end epoch

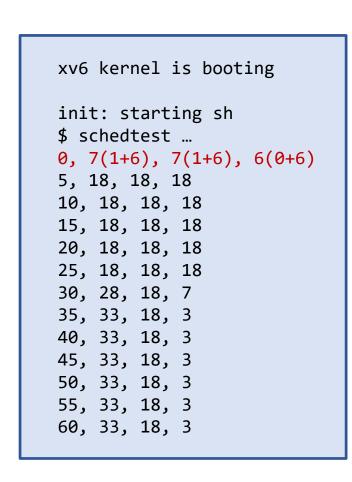
For runnable process $p \rightarrow counter = ((20 - (p \rightarrow nice)) >> 2) + 1$

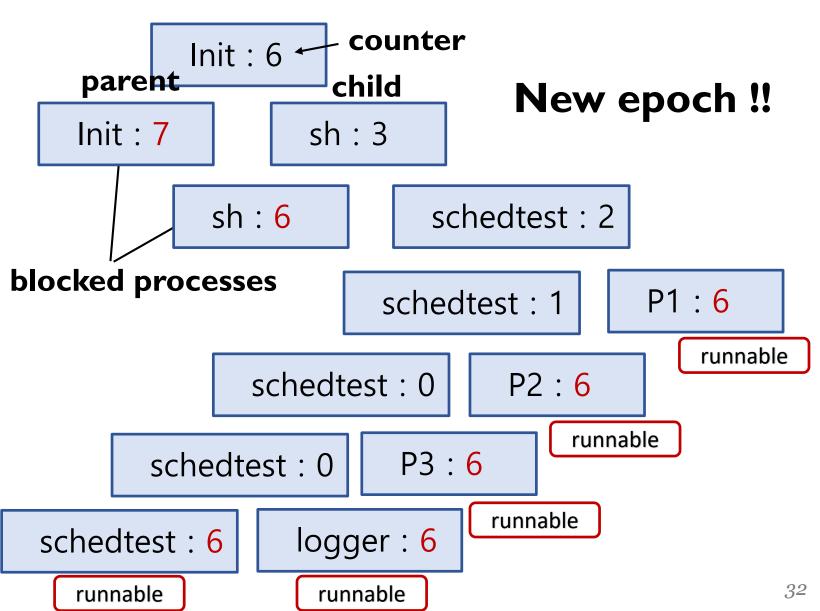
Why does the tick become like that at first?

xv6 kernel is booting init: starting sh \$ schedtest ... 0, 7, 7, 6 5, 18, 18, 18 10, 18, 18, 18 15, 18, 18, 18 20, 18, 18, 18 25, 18, 18, 18 30, 28, 18, 7 35, 33, 18, 3 40, 33, 18, 3 45, 33, 18, 3 50, 33, 18, 3 55, 33, 18, 3 60, 33, 18, 3



Why does the tick become like that at first?





Example – schedtest2

```
xv6 kernel is booting
init: starting sh
$ schedtest2
0, 7, 7, 6
5, 18, 18, 18 -> phase1
10, 18, 18, 18
15, 18, 18, 18
20, 18, 18, 18
25, 18, 18, 18
30, 28, 18, 7
35, 33, 18, 3 -> phase2
40, 33, 18, 3
45, 33, 18, 3
50, 33, 18, 3
55, 33, 18, 3
60, 27, 18, 5
65, 27, 18, 6 -> phase3
70, 27, 18, 6
```

```
75, 27, 18, 6
80, 27, 18, 6
85, 27, 18, 6
90, 24, 18, 8
95, 24, 18, 9 -> phase4
100, 24, 18, 9
105, 24, 18, 9
110, 24, 18, 9
115, 24, 18, 9
120, 21, 18, 11
125, 21, 18, 12 -> phase5
130, 21, 18, 12
135, 21, 18, 12
140, 21, 18, 12
145, 21, 18, 12
150, 21, 18, 12
```

```
Ticks
                              —— P2
                                         → P3
35
30
25
20 -
15 -
10 -
          20
                                 80
                  40
                         60
                                        100
                                                120
                                                       140
                                                               160
```

```
phase1 0/0/0
phase2 -20/0/19
phase3 -15/0/15
phase4 -10/0/10
phase5 -5/0/5
```

FAQ

- Even if you change the nice value to nice(), you do not need to change the p->counter immediately.
 - Just write the changed value when the p->nice value is used.
- What happens when there's a block in the middle?
 - $p \rightarrow counter = (p \rightarrow counter >> 1) + ((20 (p \rightarrow nice)) >> 2) + 1$
- When timer interrupt is occurred, the p->counter value may become negative once the p->counter value is reduced.
- If runnable process is not available, continue waiting without starting new epoch

Thank you!

Any questions?